

FM Packet Telemetry Format

For CubeSat “SEEDS”

English Version



Nihon University CubeSat Project

Revision	Date	Authored by	Notes
1	06/22/2006	Nobuaki Kinoshita	FM Packet Telemetry Format
2	01/09/2008	Kosuke Arita	Revised for 2 nd SEEDS
3	21/04/2008	Kosuke Arita	Considered calibration result of sensors Revised some mistakes

FM packet telemetry format for SEEDS

SEEDS has three type of FM packet telemetry format.

1. Test FM (Transmit the data with FM packet just after sensing.)
2. FM Downlink (Transmit the data that is read from EEPROM with FM packet. The data in EEPROM was stored previous mission.)
3. Any Characters Downlink (Transmit any letters up to 16 characters by uplink command)

Please get FM packet in hex number and remove "4A 51 31 59 47 55 3E 4A 51 31 59 47 56 3A" part that is converted "JQ1YGU>JQ1YGV:" into hex number. Following format is not included "4A 51 31 59 47 55 3E 4A 51 31 59 47 56 3A" part.

FM packet telemetry format:

11 22 33 33 44 44 44 44 55 55 66 66 77 77 88 88 99 AA BB BB CC CC DD DD EE EE FF FF GG GG HH HH II II JJ JJ KK KK LL LL MM MM NN NN OO OO PP PP QQ QQ TT TT UU UU VV VV WW WW XX XX YY YY ZZ ZZ aa aa bb bb cc cc dd dd

FM Packet (Test FM or FM Downlink)			
Data	Digit Number	Designation	Conversion Equation
1 ₁ 1 ₀	2	(Test FM) not in use (FM Downlink) Types of transmitted data and EEPROM number that SEEDS read	First, convert binary digit into hex number. For Example, (F8) ₁₆ ==> (1 ₄ 1 ₃ 1 ₂ 1 ₁ 1 ₀ 0 ₂ 0 ₁ 0 ₀) ₂ . Next, check the status according to following criteria. 1 ₄ System status* (0 or 1) 1 ₃ Internal temperature* (0 or 1) 1 ₂ Gyro sensor and geomagnetism sensor* (0 or 1) 1 ₁ The current from solar cell* (0 or 1) 1 ₀ External temperature* (0 or 1) 0 ₂ 0 ₁ TBD 0 ₀ the number of ROM that SEEDS read (0 or 1) [* 0: N/A ("0" is filled in the data block)] [* 1: The sensor data is stored]
2 ₁ 2 ₀	2	(Test FM) not in use (FM Downlink) Page address, that SEEDS read, in EEPROM	First, convert binary digit into hex number. Next, use only least significant bit. The value means page address which SEEDS read. For Example, (88) ₁₆ ==> (1 ₄ 0 ₃ 0 ₂ 0 ₁ 1 ₀ 0 ₂ 0 ₁ 0 ₀) ₂ . Because the value of 0 ₀ is zero, page address in EEPROM is 0.
3 ₃ 3 ₂ 3 ₁ 3 ₀	4	(Test FM) not in use (FM Downlink) ROM address, that SEEDS read, in EEPROM	This part represents ROM address which SEEDS read. The scope of data is between 0000 and FFFF.
4 ₇ 4 ₆ 4 ₅ 4 ₄ 4 ₃ 4 ₂ 4 ₁ 4 ₀	8	Satellite time	$(4_7 \times 16^7 + 4_6 \times 16^6 + 4_5 \times 16^5 + 4_4 \times 16^4 + 4_3 \times 16^3 + 4_2 \times 16^2 + 4_1 \times 16^1 + 4_0 \times 16^0) / 2$ [s]
5 ₃ 5 ₂ 5 ₁ 5 ₀	4	MPU reset times (EPS)	$5_3 \times 16^3 + 5_2 \times 16^2 + 5_1 \times 16^1 + 5_0 \times 16^0$ [times]
6 ₃ 6 ₂ 6 ₁ 6 ₀	4	MPU reset times (FMR)	$6_3 \times 16^3 + 6_2 \times 16^2 + 6_1 \times 16^1 + 6_0 \times 16^0$ [times]
7 ₃ 7 ₂ 7 ₁ 7 ₀	4	MPU reset times (C&DH)	$7_3 \times 16^3 + 7_2 \times 16^2 + 7_1 \times 16^1 + 7_0 \times 16^0$ [times]

Data	Digit Number	Designation	Conversion Equation
8 ₃ 8 ₂ 8 ₁ 8 ₀	4	MPU reset times (CW)	$8_3 \times 16^3 + 8_2 \times 16^2 + 8_1 \times 16^1 + 8_0 \times 16^0$ [times]
9 ₁ 9 ₀	2	ROM number that SEEDS stored at last time	First, convert binary digit into hex number. Next, use only least significant bit.
A ₁ A ₀	2	Page address that SEEDS stored at last time	First, convert binary digit into hex number. Next, use only least significant bit.
B ₃ B ₂ B ₁ B ₀	2	ROM address that SEEDS stored at last time	This part represents ROM address which SEEDS read. The scope of data is between 0000 and FFFF.
C ₃ C ₂ C ₁ C ₀	4	Temperature (The top of solar cell 1)	$-0.18936 \times (5 \times (C_2 \times 16^2 + C_1 \times 16^1 + C_0 \times 16^0) / 4096)^2$ $-37.767 \times (5 \times (C_2 \times 16^2 + C_1 \times 16^1 + C_0 \times 16^0) / 4096)$ $+125.76$ [deg. C]
D ₃ D ₂ D ₁ D ₀	4	Temperature (The top of solar cell 2)	$-0.008324 \times (5 \times (D_2 \times 16^2 + D_1 \times 16^1 + D_0 \times 16^0) / 4096)^2$ $-39.376 \times (5 \times (D_2 \times 16^2 + D_1 \times 16^1 + D_0 \times 16^0) / 4096)$ $+128.75$ [deg. C]
E ₃ E ₂ E ₁ E ₀	4	Temperature (The top of solar cell 3)	$-0.16644 \times (5 \times (E_2 \times 16^2 + E_1 \times 16^1 + E_0 \times 16^0) / 4096)^2$ $-38.12 \times (5 \times (E_2 \times 16^2 + E_1 \times 16^1 + E_0 \times 16^0) / 4096)$ $+127.38$ [deg. C]
F ₃ F ₂ F ₁ F ₀	4	Temperature (The top of solar cell 4)	$-0.19416 \times (5 \times (F_2 \times 16^2 + F_1 \times 16^1 + F_0 \times 16^0) / 4096)^2$ $-37.757 \times (5 \times (F_2 \times 16^2 + F_1 \times 16^1 + F_0 \times 16^0) / 4096)$ $+126.93$ [deg. C]
G ₃ G ₂ G ₁ G ₀	4	Temperature (The top of solar cell 5)	$-0.19718 \times (5 \times (G_2 \times 16^2 + G_1 \times 16^1 + G_0 \times 16^0) / 4096)^2$ $-37.966 \times (5 \times (G_2 \times 16^2 + G_1 \times 16^1 + G_0 \times 16^0) / 4096)$ $+125.64$ [deg. C]
H ₃ H ₂ H ₁ H ₀	4	Temperature (The top of solar cell 6)	$-0.44743 \times (5 \times (H_2 \times 16^2 + H_1 \times 16^1 + H_0 \times 16^0) / 4096)^2$ $-35.879 \times (5 \times (H_2 \times 16^2 + H_1 \times 16^1 + H_0 \times 16^0) / 4096)$ $+123.57$ [deg. C]
I ₃ I ₂ I ₁ I ₀	4	Solar cell 1 current	$5 \times (I_2 \times 16^2 + I_1 \times 16^1 + I_0 \times 16^0) / 4096 \times 90.90909$ [mA]
J ₃ J ₂ J ₁ J ₀	4	Solar cell 2 current	$5 \times (J_2 \times 16^2 + J_1 \times 16^1 + J_0 \times 16^0) / 4096 \times 90.90909$ [mA]
K ₃ K ₂ K ₁ K ₀	4	Solar cell 3 current	$5 \times (K_2 \times 16^2 + K_1 \times 16^1 + K_0 \times 16^0) / 4096 \times 90.90909$ [mA]
L ₃ L ₂ L ₁ L ₀	4	Solar cell 4 current	$5 \times (L_2 \times 16^2 + L_1 \times 16^1 + L_0 \times 16^0) / 4096 \times 90.90909$ [mA]
M ₃ M ₂ M ₁ M ₀	4	Solar cell 5 current	$5 \times (M_2 \times 16^2 + M_1 \times 16^1 + M_0 \times 16^0) / 4096 \times 90.90909$ [mA]
N ₃ N ₂ N ₁ N ₀	4	Solar cell 6 current	$5 \times (N_2 \times 16^2 + N_1 \times 16^1 + N_0 \times 16^0) / 4096 \times 90.90909$ [mA]
O ₃ O ₂ O ₁ O ₀	4	Li-ion batteries voltage	$5 \times (O_2 \times 16^2 + O_1 \times 16^1 + O_0 \times 16^0) / 4096$ [V]
P ₃ P ₂ P ₁ P ₀	4	Bus voltage	$5 \times (P_2 \times 16^2 + P_1 \times 16^1 + P_0 \times 16^0) / 4096$ [V]
Q ₃ Q ₂ Q ₁ Q ₀	4	Gyro sensor (x axis)	$-0.0011537 \times (5 \times (Q_2 \times 16^2 + Q_1 \times 16^1 + Q_0 \times 16^0) / 4096)^2$ $+0.88832 \times (5 \times (Q_2 \times 16^2 + Q_1 \times 16^1 + Q_0 \times 16^0) / 4096)$ -2.2173 [rad/s]
R ₃ R ₂ R ₁ R ₀	4	Gyro sensor (y axis)	$9.7079 \times 10^{-5} \times (5 \times (R_2 \times 16^2 + R_1 \times 16^1 + R_0 \times 16^0) / 4096)^2$ $+0.88422 \times (5 \times (R_2 \times 16^2 + R_1 \times 16^1 + R_0 \times 16^0) / 4096)$ -2.2133 [rad/s]
S ₃ S ₂ S ₁ S ₀	4	Gyro sensor (z axis)	$-0.0018095 \times (5 \times (S_2 \times 16^2 + S_1 \times 16^1 + S_0 \times 16^0) / 4096)^2$ $+0.88805 \times (5 \times (S_2 \times 16^2 + S_1 \times 16^1 + S_0 \times 16^0) / 4096)$ -2.2032 [rad/s]
T ₃ T ₂ T ₁ T ₀	4	Geomagnetic sensor (x axis)	$5 \times (T_2 \times 16^2 + T_1 \times 16^1 + T_0 \times 16^0) / 4096 - 2.5$ [gauss]
U ₃ U ₂ U ₁ U ₀	4	Geomagnetic sensor (y axis)	$5 \times (U_2 \times 16^2 + U_1 \times 16^1 + U_0 \times 16^0) / 4096 - 2.5$ [gauss]
V ₃ V ₂ V ₁ V ₀	4	Geomagnetic sensor (z axis)	$5 \times (V_2 \times 16^2 + V_1 \times 16^1 + V_0 \times 16^0) / 4096 - 2.5$ [gauss]

Data	Digit Number	Designation	Conversion Equation
W₃W₂W₁W₀	4	Temperature (Li-ion battery 1)	$0.15797 \times (5 \times (W_2 \times 16^2 + W_1 \times 16^1 + W_0 \times 16^0) / 4096)^2$ $-39.553 \times (5 \times (W_2 \times 16^2 + W_1 \times 16^1 + W_0 \times 16^0) / 4096)$ $+129.59[\text{deg. C}]$
X₃X₂X₁X₀	4	Temperature (Li-ion battery 2)	$0.18923 \times (5 \times (X_2 \times 16^2 + X_1 \times 16^1 + X_0 \times 16^0) / 4096)^2$ $-39.27 \times (5 \times (X_2 \times 16^2 + X_1 \times 16^1 + X_0 \times 16^0) / 4096)$ $+128.33[\text{deg. C}]$
Y₃Y₂Y₁Y₀	4	Temperature (Gyro sensor [x axis])	$10.292 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)^6$ $-173.25 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)^5$ $+1194.3 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)^4$ $-4312.6 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)^3$ $+8600.5 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)^2$ $-9020.1 \times (5 \times (Y_2 \times 16^2 + Y_1 \times 16^1 + Y_0 \times 16^0) / 4096)$ $+3962.8 [\text{deg. C}]$
Z₃Z₂Z₁Z₀	4	Temperature (Gyro sensor [y axis])	$-0.19176 \times (5 \times (R_2 \times 16^2 + R_1 \times 16^1 + R_0 \times 16^0) / 4096)^2$ $-37.747 \times (5 \times (R_2 \times 16^2 + R_1 \times 16^1 + R_0 \times 16^0) / 4096)$ $+125.06 [\text{deg. C}]$
a₃a₂a₁a₀	4	Temperature (Gyro sensor [z axis])	$-0.81874 \times (5 \times (a_2 \times 16^2 + a_1 \times 16^1 + a_0 \times 16^0) / 4096)^2$ $-34.744 \times (5 \times (a_2 \times 16^2 + a_1 \times 16^1 + a_0 \times 16^0) / 4096)$ $+122.46 [\text{deg. C}]$
b₃b₂b₁b₀	4	Temperature (Digi-talker)	$-0.084633 \times (5 \times (b_2 \times 16^2 + b_1 \times 16^1 + b_0 \times 16^0) / 4096)^2$ $-37.991 \times (5 \times (b_2 \times 16^2 + b_1 \times 16^1 + b_0 \times 16^0) / 4096)$ $+124.25 [\text{deg. C}]$
c₃c₂c₁c₀	4	Temperature (Transmitter)	$-0.38082 \times (5 \times (c_2 \times 16^2 + c_1 \times 16^1 + c_0 \times 16^0) / 4096)^2$ $-36.125 \times (5 \times (c_2 \times 16^2 + c_1 \times 16^1 + c_0 \times 16^0) / 4096)$ $+121.31 [\text{deg. C}]$
d₃d₂d₁d₀	4	Temperature (Receiver)	$-0.062626 \times (5 \times (d_2 \times 16^2 + d_1 \times 16^1 + d_0 \times 16^0) / 4096)^2$ $-38.305 \times (5 \times (d_2 \times 16^2 + d_1 \times 16^1 + d_0 \times 16^0) / 4096)$ $+126.89 [\text{deg. C}]$

Any Characters Downlink
JQ1YGU>JQ1YGV:ABCDEFGHIJKLMN OP (SEEDS can transmit up to 120 characters by uplink command)

The number of solar cells and the coordinate system of SEEDS

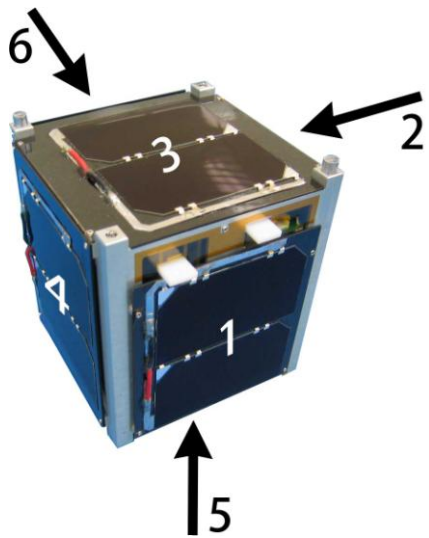


Fig.1 The number of solar cells of SEEDS

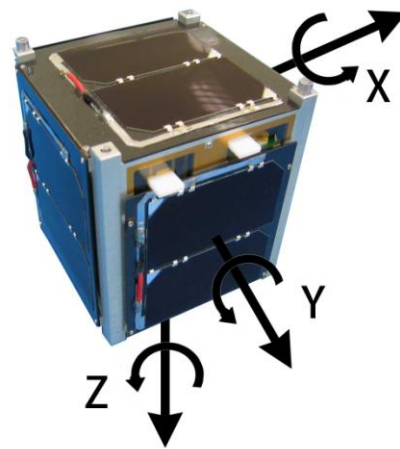


Fig.2 The coordinate system of SEEDS

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