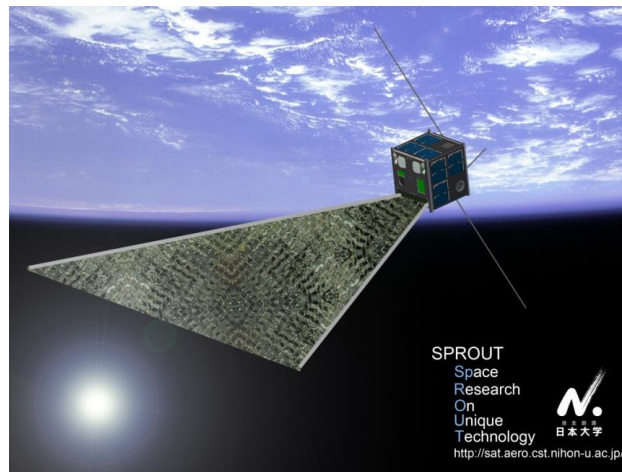


# FM Telemetry Data Format

For "SPROUT" CDH1

Revision B

Date : 2014/6/3



Nihon University CubeSat Project

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## Revision

Revision	Date	Revised point	Authored by
	2014/4/25		Yusuke Yamaguchi
A	2014/5/23	Revised telemetry format	Kento Ohinata
B	2014/6/3	Revised telemetry format	Kento Ohinata

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# 1. Communication Protocol

This is the protocol of FM communication of SPROUT. And, you need to see our HP to know which mode SPROUT is in now.

SPROUT FM Downlink	
Band rate and type	437.525MHz
	1200bps FM/AFSK
	9600bps FM/GMSK
	437.600MHz
	1200bps FM/AFSK

# 2. FM Telemetry Format

These is seven mode of SPROUT FM Telemetry.

(1) Test FM

Send real time sensor data by FM packet

(2)CDH1 Sensing Data

Send CDH1 sensor data which saved at FEPR0M by FM packet.

(3)INF Sensing Data(Pressure, Temperature)

Send INF sensor data (Pressure Sensor, Temperature Sensor) which saved at FEPR0M by FM packet.

(4)INF Sensing Data(Piezo)

Send INF sensor data(Piezo Sensor) which saved at FEPR0M by FM packet.

(5)CAM Row Data

Send camera data(row data) which saved at FEPR0M by FM packet.

(6)CAM Thumbnail Data

Send camera data(Compressed data) which saved at FEPR0M by FM packet.

(7)ADC Data

Send ADC sensor data which saved at FEPR0M by FM packet.

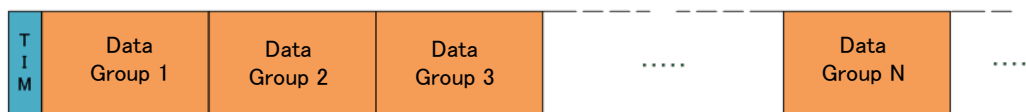
This paper provide FM packet formant only "Test FM" and "CDH1 sensing data"

## 2.1. FM downlink data structure

These are data structure for FM downlink except "Test FM".

Type of FM packet telemetry	
<b>Call sign</b>	"SPROUT>JQ1ZJQ:"
<b>DBN</b>	Data Block Number
<b>TIM</b>	Time Data Group.
<b>Data group</b>	Data group number for one sensing.
<b>CR</b>	Carriage Return "0X0D"

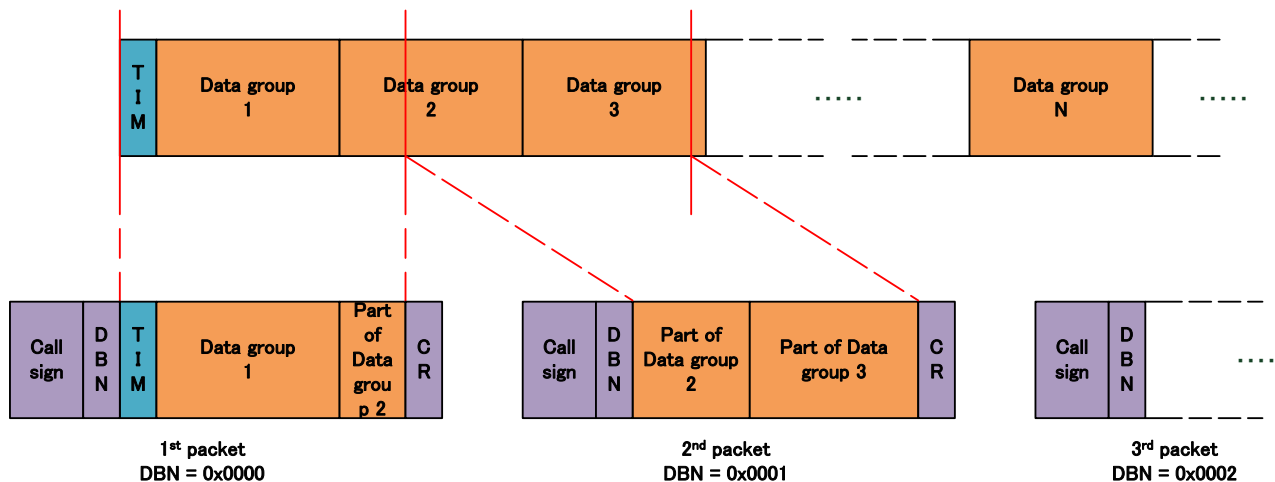
Put sensing time is N(times). The data saved in FEPR0M is below. And, satellite time is header of data structure.



The data group saved in FEPR0M

This saved data group will send downlink by FM packet.

The data quantity of data group and single packet is different. So, FM packet downlink such as this figure below.



The maximum data of single packet is 224[byte]. We use DBN (Data Block Number) method. The number of data group and single packet is not same quantity. So the data break into couple blocks. We call this block is "Data Block".

A DBN shows downlink packet number (This number is serial number which saved in FEPRM). Also, A satellite time shows time which is inside satellite. Each number formed hexadecimal number.

DBN	TIM
0 <sub>3</sub> 0 <sub>2</sub> 0 <sub>1</sub> 0 <sub>0</sub>	1 <sub>7</sub> 1 <sub>6</sub> 1 <sub>5</sub> 1 <sub>4</sub> 1 <sub>3</sub> 1 <sub>2</sub> 1 <sub>1</sub> 1 <sub>0</sub>

This calculation is below.

FM downlink calculation				
Group	data	Word(s)	Mean	Calculation
DBN	0 <sub>3</sub> 0 <sub>2</sub> 0 <sub>1</sub> 0 <sub>0</sub>	4	Data block number	$0_3 \times 16^3 + 0_2 \times 16^2 + 0_1 \times 16^1 + 0_0 \times 16^0$ [blocks]
TIM	1 <sub>7</sub> 1 <sub>6</sub> 1 <sub>5</sub> 1 <sub>4</sub> 1 <sub>3</sub> 1 <sub>2</sub> 1 <sub>1</sub> 1 <sub>0</sub>	8	Satellite time	$(1_7 \times 16^7 + 1_6 \times 16^6 + 1_5 \times 16^5 + 1_4 \times 16^4 + 1_3 \times 16^3 + 1_2 \times 16^2 + 1_1 \times 16^1 + 1_0 \times 16^0) / 10$ [s]

The satellite time gives only start of sensing. And, An interval time between sensing is only able to see at telemetry format (Chaper 3 testFM ,4 CDH1 sensing). However, this cycle can change by us. So you have to see our web site to know this information.

Usually, single packet is contain 224[byte] (448 words)for SPROUT. However , we can change packet number. You can see our website to know this information.

## 2.2. Notification

There is 4 things have to be checked our Operation site to use FM telemetry.

### (1) Communication mode

This shows FM communication mode.

### (2) Sensing start time

Sensing start time is only give top of DBN. You can see our website to know FM sensing start time.

### (3) Sampling cycle

The time between sensing(sampling cycle)is written on(chapter 3,4). But, this cycle is able to change.

### (4) Number of single packet

This is the number(s) of byte contain single packet. Normally, this number is 224[byte](448 words). But it is able to change.

(Operation site: <http://sat.aero.cst.nihon-u.ac.jp/wordpress/>)

### 3. Test FM

**JQ1ZJQ** > **SPROUT**: Data 0x0D  
Callsign                      Satellite name                      Carriage return

Test FM data group	
<b>HKD</b>	Housekeeping Data Group
<b>STA</b>	Status Data Group
<b>TIM</b>	Time Data Group
<b>RES</b>	Reset Count Data Group

If FM downlink is Test FM. It is need to transform row data to binary data after header call sign.

Data group(362 words)	
0 <sub>3</sub> 0 <sub>2</sub> 0 <sub>1</sub> 0 <sub>0</sub> 1 <sub>3</sub> 1 <sub>2</sub> 1 <sub>1</sub> 1 <sub>0</sub> 2 <sub>3</sub> 2 <sub>2</sub> 2 <sub>1</sub> 2 <sub>0</sub> 3 <sub>3</sub> 3 <sub>2</sub> 3 <sub>1</sub> 3 <sub>0</sub> 4 <sub>3</sub> 4 <sub>2</sub> 4 <sub>1</sub> 4 <sub>0</sub> 5 <sub>3</sub> 5 <sub>2</sub> 5 <sub>1</sub> 5 <sub>0</sub> 6 <sub>3</sub> 6 <sub>2</sub> 6 <sub>1</sub> 6 <sub>0</sub> 7 <sub>3</sub> 7 <sub>2</sub> 7 <sub>1</sub> 7 <sub>0</sub> 8 <sub>3</sub> 8 <sub>2</sub> 8 <sub>1</sub> 8 <sub>0</sub> 9 <sub>3</sub> 9 <sub>2</sub> 9 <sub>1</sub> 9 <sub>0</sub> a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub> b <sub>3</sub> b <sub>2</sub> b <sub>1</sub> b <sub>0</sub> c <sub>3</sub> c <sub>2</sub> c <sub>1</sub> c <sub>0</sub> d <sub>3</sub> d <sub>2</sub> d <sub>1</sub> d <sub>0</sub> e <sub>3</sub> e <sub>2</sub> e <sub>1</sub> e <sub>0</sub> f <sub>3</sub> f <sub>2</sub> f <sub>1</sub> f <sub>0</sub> g <sub>3</sub> g <sub>2</sub> g <sub>1</sub> g <sub>0</sub> h <sub>3</sub> h <sub>2</sub> h <sub>1</sub> h <sub>0</sub> i <sub>3</sub> i <sub>2</sub> i <sub>1</sub> i <sub>0</sub> j <sub>3</sub> j <sub>2</sub> j <sub>1</sub> j <sub>0</sub> k <sub>3</sub> k <sub>2</sub> k <sub>1</sub> k <sub>0</sub> l <sub>3</sub> l <sub>2</sub> l <sub>1</sub> l <sub>0</sub> m <sub>3</sub> m <sub>2</sub> m <sub>1</sub> m <sub>0</sub> n <sub>3</sub> n <sub>2</sub> n <sub>1</sub> n <sub>0</sub> o <sub>3</sub> o <sub>2</sub> o <sub>1</sub> o <sub>0</sub> p <sub>3</sub> p <sub>2</sub> p <sub>1</sub> p <sub>0</sub> q <sub>3</sub> q <sub>2</sub> q <sub>1</sub> q <sub>0</sub> r <sub>3</sub> r <sub>2</sub> r <sub>1</sub> r <sub>0</sub> s <sub>3</sub> s <sub>2</sub> s <sub>1</sub> s <sub>0</sub> t <sub>3</sub> t <sub>2</sub> t <sub>1</sub> t <sub>0</sub> u <sub>3</sub> u <sub>2</sub> u <sub>1</sub> u <sub>0</sub> v <sub>3</sub> v <sub>2</sub> v <sub>1</sub> v <sub>0</sub> w <sub>3</sub> w <sub>2</sub> w <sub>1</sub> w <sub>0</sub> x <sub>3</sub> x <sub>2</sub> x <sub>1</sub> x <sub>0</sub> y <sub>3</sub> y <sub>2</sub> y <sub>1</sub> y <sub>0</sub> z <sub>3</sub> z <sub>2</sub> z <sub>1</sub> z <sub>0</sub> A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub> B <sub>3</sub> B <sub>2</sub> B <sub>1</sub> B <sub>0</sub> C <sub>3</sub> C <sub>2</sub> C <sub>1</sub> C <sub>0</sub> D <sub>3</sub> D <sub>2</sub> D <sub>1</sub> D <sub>0</sub> E <sub>3</sub> E <sub>2</sub> E <sub>1</sub> E <sub>0</sub> F <sub>3</sub> F <sub>2</sub> F <sub>1</sub> F <sub>0</sub> G <sub>3</sub> G <sub>2</sub> G <sub>1</sub> G <sub>0</sub> H <sub>3</sub> H <sub>2</sub> H <sub>1</sub> H <sub>0</sub> I <sub>3</sub> I <sub>2</sub> I <sub>1</sub> I <sub>0</sub> J <sub>3</sub> J <sub>2</sub> J <sub>1</sub> J <sub>0</sub> K <sub>3</sub> K <sub>2</sub> K <sub>1</sub> K <sub>0</sub> L <sub>3</sub> L <sub>2</sub> L <sub>1</sub> L <sub>0</sub> M <sub>3</sub> M <sub>2</sub> M <sub>1</sub> M <sub>0</sub> N <sub>3</sub> N <sub>2</sub> N <sub>1</sub> N <sub>0</sub> O <sub>3</sub> O <sub>2</sub> O <sub>1</sub> O <sub>0</sub> P <sub>3</sub> P <sub>2</sub> P <sub>1</sub> P <sub>0</sub> Q <sub>3</sub> Q <sub>2</sub> Q <sub>1</sub> Q <sub>0</sub> R <sub>3</sub> R <sub>2</sub> R <sub>1</sub> R <sub>0</sub> S <sub>3</sub> S <sub>2</sub> S <sub>1</sub> S <sub>0</sub> T <sub>3</sub> T <sub>2</sub> T <sub>1</sub> T <sub>0</sub> U <sub>3</sub> U <sub>2</sub> U <sub>1</sub> U <sub>0</sub> V <sub>3</sub> V <sub>2</sub> V <sub>1</sub> V <sub>0</sub> W <sub>3</sub> W <sub>2</sub> W <sub>1</sub> W <sub>0</sub> X <sub>3</sub> X <sub>2</sub> X <sub>1</sub> X <sub>0</sub> Y <sub>3</sub> Y <sub>2</sub> Y <sub>1</sub> Y <sub>0</sub> Z <sub>3</sub> Z <sub>2</sub> Z <sub>1</sub> Z <sub>0</sub> a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub> β <sub>3</sub> β <sub>2</sub> β <sub>1</sub> β <sub>0</sub> γ <sub>3</sub> γ <sub>2</sub> γ <sub>1</sub> γ <sub>0</sub> δ <sub>3</sub> δ <sub>2</sub> δ <sub>1</sub> δ <sub>0</sub> ε <sub>3</sub> ε <sub>2</sub> ε <sub>1</sub> ε <sub>0</sub> ζ <sub>3</sub> ζ <sub>2</sub> ζ <sub>1</sub> ζ <sub>0</sub> η <sub>3</sub> η <sub>2</sub> η <sub>1</sub> η <sub>0</sub> θ <sub>3</sub> θ <sub>2</sub> θ <sub>1</sub> θ <sub>0</sub> ι <sub>3</sub> ι <sub>2</sub> ι <sub>1</sub> ι <sub>0</sub> κ <sub>3</sub> κ <sub>2</sub> κ <sub>1</sub> κ <sub>0</sub> λ <sub>3</sub> λ <sub>2</sub> λ <sub>1</sub> λ <sub>0</sub> μ <sub>3</sub> μ <sub>2</sub> μ <sub>1</sub> μ <sub>0</sub> ν <sub>3</sub> ν <sub>2</sub> ν <sub>1</sub> ν <sub>0</sub> ξ <sub>3</sub> ξ <sub>2</sub> ξ <sub>1</sub> ξ <sub>0</sub> ο <sub>3</sub> ο <sub>2</sub> ο <sub>1</sub> ο <sub>0</sub> π <sub>3</sub> π <sub>2</sub> π <sub>1</sub> π <sub>0</sub> ρ <sub>3</sub> ρ <sub>2</sub> ρ <sub>1</sub> ρ <sub>0</sub> σ <sub>3</sub> σ <sub>2</sub> σ <sub>1</sub> σ <sub>0</sub> τ <sub>3</sub> τ <sub>2</sub> τ <sub>1</sub> τ <sub>0</sub> υ <sub>3</sub> υ <sub>2</sub> υ <sub>1</sub> υ <sub>0</sub> φ <sub>3</sub> φ <sub>2</sub> φ <sub>1</sub> φ <sub>0</sub> χ <sub>3</sub> χ <sub>2</sub> χ <sub>1</sub> χ <sub>0</sub> ψ <sub>3</sub> ψ <sub>2</sub> ψ <sub>1</sub> ψ <sub>0</sub> ω <sub>3</sub> ω <sub>2</sub> ω <sub>1</sub> ω <sub>0</sub> A <sub>23</sub> A <sub>22</sub> A <sub>21</sub> A <sub>20</sub> A <sub>19</sub> A <sub>18</sub> A <sub>17</sub> A <sub>16</sub> A <sub>15</sub> A <sub>14</sub> A <sub>13</sub> A <sub>12</sub> A <sub>11</sub> A <sub>10</sub> A <sub>9</sub> A <sub>8</sub> A <sub>7</sub> A <sub>6</sub> A <sub>5</sub> A <sub>4</sub> A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub>	

Give the "0X0D" code at end of downlink data.

All data formed hex except "HKD" data. This data (on the figure below) is decimal number.

Test FM packet structure (total362 words)				
Group	data	Word(s)	Mean	Calculation
HKD	0 <sub>3</sub> 0 <sub>2</sub> 0 <sub>1</sub> 0 <sub>0</sub>	4	+X Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	1 <sub>3</sub> 1 <sub>2</sub> 1 <sub>1</sub> 1 <sub>0</sub>	4	-X Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	2 <sub>3</sub> 2 <sub>2</sub> 2 <sub>1</sub> 2 <sub>0</sub>	4	-X Solar cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	3 <sub>3</sub> 3 <sub>2</sub> 3 <sub>1</sub> 3 <sub>0</sub>	4	-Y Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	4 <sub>3</sub> 4 <sub>2</sub> 4 <sub>1</sub> 4 <sub>0</sub>	4	-Y Solar cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	5 <sub>3</sub> 5 <sub>2</sub> 5 <sub>1</sub> 5 <sub>0</sub>	4	-Y Solar cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	6 <sub>3</sub> 6 <sub>2</sub> 6 <sub>1</sub> 6 <sub>0</sub>	4	+Y Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	7 <sub>3</sub> 7 <sub>2</sub> 7 <sub>1</sub> 7 <sub>0</sub>	4	+Y Solar cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	8 <sub>3</sub> 8 <sub>2</sub> 8 <sub>1</sub> 8 <sub>0</sub>	4	+Y Solar cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	9 <sub>3</sub> 9 <sub>2</sub> 9 <sub>1</sub> 9 <sub>0</sub>	4	+Z Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub>	4	+Z Solar cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	b <sub>3</sub> b <sub>2</sub> b <sub>1</sub> b <sub>0</sub>	4	+Z Solar cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	c <sub>3</sub> c <sub>2</sub> c <sub>1</sub> c <sub>0</sub>	4	-Z Solar cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]

Group	data	Word(s)	Mean	Calculation
HKD	d <sub>3</sub> d <sub>2</sub> d <sub>1</sub> d <sub>0</sub>	4	- Z Solar cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	e <sub>3</sub> e <sub>2</sub> e <sub>1</sub> e <sub>0</sub>	4	- Z Solar cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	f <sub>3</sub> f <sub>2</sub> f <sub>1</sub> f <sub>0</sub>	4	Bus current	$(5 \times x)/(4096 \times 0.5)$ [A]
	g <sub>3</sub> g <sub>2</sub> g <sub>1</sub> g <sub>0</sub>	4	Bus voltage	$(5 \times x)/4096$ [V]
	h <sub>3</sub> h <sub>2</sub> h <sub>1</sub> h <sub>0</sub>	4	Temperature (Satellite surface + X)	$0.282 \times ((5 \times x)/4096)^2 - 38.98 \times (5 \times x)/4096 + 101.68$ [deg. C]
	i <sub>3</sub> i <sub>2</sub> i <sub>1</sub> i <sub>0</sub>	4	Temperature (Satellite surface + Y)	$0.5777 \times ((5 \times x)/4096)^2 - 40.453 \times (5 \times x)/4096 + 99.226$ [deg. C]
	j <sub>3</sub> j <sub>2</sub> j <sub>1</sub> j <sub>0</sub>	4	Temperature (Satellite surface + Z)	$0.6493 \times ((5 \times x)/4096)^2 - 39.896 \times (5 \times x)/4096 + 98.469$ [deg. C]
	k <sub>3</sub> k <sub>2</sub> k <sub>1</sub> k <sub>0</sub>	4	Temperature (Satellite surface - X)	$0.4105 \times ((5 \times x)/4096)^2 - 39.074 \times (5 \times x)/4096 + 97.993$ [deg. C]
	l <sub>3</sub> l <sub>2</sub> l <sub>1</sub> l <sub>0</sub>	4	Temperature (Satellite surface - Y)	$0.4383 \times ((5 \times x)/4096)^2 - 40.076 \times (5 \times x)/4096 + 98.771$ [deg. C]
	m <sub>3</sub> m <sub>2</sub> m <sub>1</sub> m <sub>0</sub>	4	Temperature (Satellite surface - Z)	$0.2982 \times ((5 \times x)/4096)^2 - 38.98 \times (5 \times x)/4096 + 99.769$ [deg. C]
	n <sub>3</sub> n <sub>2</sub> n <sub>1</sub> n <sub>0</sub>	4	Temperature(Battery 2)	$0.4342 \times ((5 \times x)/4096)^2 - 41.236 \times (5 \times x)/4096 + 103.46$ [deg. C]
	o <sub>3</sub> o <sub>2</sub> o <sub>1</sub> o <sub>0</sub>	4	Temperature(Battery 1)	$0.3995 \times ((5 \times x)/4096)^2 - 40.088 \times (5 \times x)/4096 + 100.84$ [deg. C]
	p <sub>3</sub> p <sub>2</sub> p <sub>1</sub> p <sub>0</sub>	4	Temperature (Reciver2)	$0.3285 \times ((5 \times x)/4096)^2 - 39.376 \times (5 \times x)/4096 + 98.91$ [deg. C]
	q <sub>3</sub> q <sub>2</sub> q <sub>1</sub> q <sub>0</sub>	4	Temperature (Trensmitter2)	$0.2311 \times ((5 \times x)/4096)^2 - 38.955 \times (5 \times x)/4096 + 100.19$ [deg. C]
	r <sub>3</sub> r <sub>2</sub> r <sub>1</sub> r <sub>0</sub>	4	Temperature (Reciver 1)	$0.3281 \times ((5 \times x)/4096)^2 - 39.035 \times (5 \times x)/4096 + 97.608$ [deg. C]
	s <sub>3</sub> s <sub>2</sub> s <sub>1</sub> s <sub>0</sub>	4	Temperature (Transmitter 1)	$0.2946 \times ((5 \times x)/4096)^2 - 39.537 \times (5 \times x)/4096 + 99.7$ [deg. C]
	t <sub>3</sub> t <sub>2</sub> t <sub>1</sub> t <sub>0</sub>	4	Temperature (Gyro sensor Y axis)	$2.1507 \times ((5 \times x)/4096)^2 - 46.004 \times (5 \times x)/4096 + 106.55$ [deg. C]
	u <sub>3</sub> u <sub>2</sub> u <sub>1</sub> u <sub>0</sub>	4	Temperature (Gyro sensor X axis)	$0.7854 \times ((5 \times x)/4096)^2 - 41.015 \times (5 \times x)/4096 + 100.05$ [deg. C]
	v <sub>3</sub> v <sub>2</sub> v <sub>1</sub> v <sub>0</sub>	4	Temperature (Gyro sensor Z axis)	$0.9648 \times ((5 \times x)/4096)^2 - 39.886 \times (5 \times x)/4096 + 108.37$ [deg. C]
	w <sub>3</sub> w <sub>2</sub> w <sub>1</sub> w <sub>0</sub>	4	Temperature (Magnetic field sensor)	$0.0728 \times ((5 \times x)/4096)^2 - 36.191 \times (5 \times x)/4096 + 95.367$ [deg. C]
	x <sub>3</sub> x <sub>2</sub> x <sub>1</sub> x <sub>0</sub>	4	Temperature (Magnetic valve 1)	$0.1777 \times ((5 \times x)/4096)^2 - 38.862 \times (5 \times x)/4096 + 98.819$ [deg. C]
	y <sub>3</sub> y <sub>2</sub> y <sub>1</sub> y <sub>0</sub>	4	Temperature (storage box top)	$0.7649 \times ((5 \times x)/4096)^2 - 41.38 \times (5 \times x)/4096 + 101.98$ [deg. C]
	z <sub>3</sub> z <sub>2</sub> z <sub>1</sub> z <sub>0</sub>	4	Temperature (ADC board)	$0.2936 \times ((5 \times x)/4096)^2 - 39.207 \times (5 \times x)/4096 + 99.713$ [deg. C]
	A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub>	4	Temperature (EPS board)	$0.3051 \times ((5 \times x)/4096)^2 - 39.009 \times (5 \times x)/4096 + 99.257$ [deg. C]
	B <sub>3</sub> B <sub>2</sub> B <sub>1</sub> B <sub>0</sub>	4	Temperature (CDH1 board)	$0.3241 \times ((5 \times x)/4096)^2 - 39.444 \times (5 \times x)/4096 + 100.56$ [deg. C]
	C <sub>3</sub> C <sub>2</sub> C <sub>1</sub> C <sub>0</sub>	4	Temperature (CAM3 board)	$0.3862 \times ((5 \times x)/4096)^2 - 39.157 \times (5 \times x)/4096 + 100.05$ [deg. C]
	D <sub>3</sub> D <sub>2</sub> D <sub>1</sub> D <sub>0</sub>	4	Temperature (FMR1 board)	$0.3366 \times ((5 \times x)/4096)^2 - 39.025 \times (5 \times x)/4096 + 98.665$ [deg. C]
	E <sub>3</sub> E <sub>2</sub> E <sub>1</sub> E <sub>0</sub>	4	Temperature (bottom of membrane)	$0.0832 \times ((5 \times x)/4096)^2 - 38.109 \times (5 \times x)/4096 + 96.654$ [deg. C]
	F <sub>3</sub> F <sub>2</sub> F <sub>1</sub> F <sub>0</sub>	4	Temperature (InflatableTube 1)	$0.1625 \times ((5 \times x)/4096)^2 - 38.356 \times (5 \times x)/4096 + 98.533$ [deg. C]
	G <sub>3</sub> G <sub>2</sub> G <sub>1</sub> G <sub>0</sub>	4	Temperature (InflatableTube2)	$0.0357 \times ((5 \times x)/4096)^2 - 37.908 \times (5 \times x)/4096 + 98.005$ [deg. C]

Group	data	Word(s)	Mean	Calculation
HKD	H <sub>3</sub> H <sub>2</sub> H <sub>1</sub> H <sub>0</sub>	4	Temperature (Inside pipe)	$0.3021 \times ((5 \times x)/4096)^2 - 39.42 \times (5 \times x)/4096 + 98.922$ [deg. C]
	I <sub>3</sub> I <sub>2</sub> I <sub>1</sub> I <sub>0</sub>	4	Temperature (Inside storage box)	$-0.0318 \times ((5 \times x)/4096)^2 - 37.221 \times (5 \times x)/4096 + 98.686$ [deg. C]
	J <sub>3</sub> J <sub>2</sub> J <sub>1</sub> J <sub>0</sub>	4	Pressure sensor Primary pressure	$(20689.66 \times x)/4096$ [kPa]
	K <sub>3</sub> K <sub>2</sub> K <sub>1</sub> K <sub>0</sub>	4	Pressure sensor Secondly pressure	$(206.90 \times x)/4096$ [kPa]
	L <sub>3</sub> L <sub>2</sub> L <sub>1</sub> L <sub>0</sub>	4	No-Data	-
	M <sub>3</sub> M <sub>2</sub> M <sub>1</sub> M <sub>0</sub>	4	Magnetic field sensor Ref value	$V_{ref} = (5 \times x)/4096$ Ref ( $V_{ref}$ )value uses for calculate parameter of magnetic field sensor
	N <sub>3</sub> N <sub>2</sub> N <sub>1</sub> N <sub>0</sub>	4	Magnetic field sensor Y axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	O <sub>3</sub> O <sub>2</sub> O <sub>1</sub> O <sub>0</sub>	4	Magnetic field sensor X axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	P <sub>3</sub> P <sub>2</sub> P <sub>1</sub> P <sub>0</sub>	4	Magnetic field sensor Z axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	Q <sub>3</sub> Q <sub>2</sub> Q <sub>1</sub> Q <sub>0</sub>	4	Gyro sensor Y axis	$((5 \times x)/4096 - 2.4824)/1.1288$ [rad/s]
	R <sub>3</sub> R <sub>2</sub> R <sub>1</sub> R <sub>0</sub>	4	Gyro sensor X axis	$-((5 \times x)/4096 - 2.4913)/1.1309$ [rad/s]
	S <sub>3</sub> S <sub>2</sub> S <sub>1</sub> S <sub>0</sub>	4	Gyro sensor Z axis	$((5 \times x)/4096 - 2.4752)/1.1199$ [rad/s]
	T <sub>3</sub> T <sub>2</sub> T <sub>1</sub> T <sub>0</sub>	4	No-Data	-
	U <sub>3</sub> U <sub>2</sub> U <sub>1</sub> U <sub>0</sub>	4	Sun sensor 1 +X	$(5 \times x)/4096$ [V]
	V <sub>3</sub> V <sub>2</sub> V <sub>1</sub> V <sub>0</sub>	4	Sun sensor 1 -X	$(5 \times x)/4096$ [V]
	W <sub>3</sub> W <sub>2</sub> W <sub>1</sub> W <sub>0</sub>	4	Sun sensor 1 +Y	$(5 \times x)/4096$ [V]
	X <sub>3</sub> X <sub>2</sub> X <sub>1</sub> X <sub>0</sub>	4	Sun sensor 1 -Y	$(5 \times x)/4096$ [V]
	Y <sub>3</sub> Y <sub>2</sub> Y <sub>1</sub> Y <sub>0</sub>	4	Sun sensor 2 +X	$(5 \times x)/4096$ [V]
	Z <sub>3</sub> Z <sub>2</sub> Z <sub>1</sub> Z <sub>0</sub>	4	Sun sensor 2 -X	$(5 \times x)/4096$ [V]
	a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub>	4	Sun sensor 2 +Y	$(5 \times x)/4096$ [V]
	β <sub>3</sub> β <sub>2</sub> β <sub>1</sub> β <sub>0</sub>	4	Sun sensor 2 -Y	$(5 \times x)/4096$ [V]
	γ <sub>3</sub> γ <sub>2</sub> γ <sub>1</sub> γ <sub>0</sub>	4	Sun sensor 4 -Y	$(5 \times x)/4096$ [V]
	δ <sub>3</sub> δ <sub>2</sub> δ <sub>1</sub> δ <sub>0</sub>	4	Sun sensor 4 +Y	$(5 \times x)/4096$ [V]
	ε <sub>3</sub> ε <sub>2</sub> ε <sub>1</sub> ε <sub>0</sub>	4	Sun sensor 4 -X	$(5 \times x)/4096$ [V]
	ζ <sub>3</sub> ζ <sub>2</sub> ζ <sub>1</sub> ζ <sub>0</sub>	4	Sun sensor 4 +X	$(5 \times x)/4096$ [V]
	η <sub>3</sub> η <sub>2</sub> η <sub>1</sub> η <sub>0</sub>	4	Sun sensor 3 -Y	$(5 \times x)/4096$ [V]
	θ <sub>3</sub> θ <sub>2</sub> θ <sub>1</sub> θ <sub>0</sub>	4	Sun sensor 3 +Y	$(5 \times x)/4096$ [V]
	ι <sub>3</sub> ι <sub>2</sub> ι <sub>1</sub> ι <sub>0</sub>	4	Sun sensor 3 -X	$(5 \times x)/4096$ [V]
	κ <sub>3</sub> κ <sub>2</sub> κ <sub>1</sub> κ <sub>0</sub>	4	Sun sensor 3 +X	$(5 \times x)/4096$ [V]
	λ <sub>3</sub> λ <sub>2</sub> λ <sub>1</sub> λ <sub>0</sub>	4	Sun sensor 6 -Y	$(5 \times x)/4096$ [V]
	μ <sub>3</sub> μ <sub>2</sub> μ <sub>1</sub> μ <sub>0</sub>	4	Sun sensor 6 +Y	$(5 \times x)/4096$ [V]
	ν <sub>3</sub> ν <sub>2</sub> ν <sub>1</sub> ν <sub>0</sub>	4	Sun sensor 6 -X	$(5 \times x)/4096$ [V]
	ξ <sub>3</sub> ξ <sub>2</sub> ξ <sub>1</sub> ξ <sub>0</sub>	4	Sun sensor 6 +X	$(5 \times x)/4096$ [V]
	ο <sub>3</sub> ο <sub>2</sub> ο <sub>1</sub> ο <sub>0</sub>	4	Sun sensor 5 -Y	$(5 \times x)/4096$ [V]
π <sub>3</sub> π <sub>2</sub> π <sub>1</sub> π <sub>0</sub>	4	Sun sensor 5 +Y	$(5 \times x)/4096$ [V]	
ρ <sub>3</sub> ρ <sub>2</sub> ρ <sub>1</sub> ρ <sub>0</sub>	4	Sun sensor 5 -X	$(5 \times x)/4096$ [V]	
σ <sub>3</sub> σ <sub>2</sub> σ <sub>1</sub> σ <sub>0</sub>	4	Sun sensor 5 +X	$(5 \times x)/4096$ [V]	
STA	T <sub>1</sub> T <sub>0</sub>	2	Shunt 1 ON/OFF	Use T <sub>0</sub> Number T <sub>0</sub> = 0x0 : shunt 1 OFF T <sub>0</sub> = 0x1 : shunt 1 ON
	U <sub>1</sub> U <sub>0</sub>	2	Shunt 2 ON/OFF	Use U <sub>0</sub> number U <sub>0</sub> = 0x0 : shunt 2 OFF U <sub>0</sub> = 0x1 : shunt 2 ON
	Φ <sub>1</sub> Φ <sub>0</sub>	2	ADC Activation	Use Φ <sub>0</sub> number Φ <sub>0</sub> = 0x0 : ADC Stop Φ <sub>0</sub> = 0x1 : ADC activate



Group	data	Word(s)	Mean	Calculation
STA	$\chi_1\chi_0$	2	CAM1,2 Activation	Use $\chi_1$ number $\chi_0 = 0x0$ : CAM1,2Stop $\chi_0 = 0x1$ : CAM1,2activate
	$\psi_1\psi_0$	2	CAM3 Activation	Use $\psi_0$ number. $\psi_0 = 0x0$ : CAM3Stop $\psi_0 = 0x1$ : CAM3activate
TIM	$\omega_7\omega_6\omega_5\omega_4\omega_3\omega_2\omega_1\omega_0$	8	Satellite time	$(\omega_7 \times 16^7 + \omega_6 \times 16^6 + \omega_5 \times 16^5 + \omega_4 \times 16^4 + \omega_3 \times 16^3 + \omega_2 \times 16^2 + \omega_1 \times 16^1 + \omega_0 \times 16^0) / 10$ [s]
RES	$A_{23}A_{22}A_{21}A_{20}A_{19}A_{18}$ $A_{17}A_{16}A_{15}A_{14}A_{13}A_{12}$ $A_{11}A_{10}A_9A_8A_7A_6A_5A_4$ $A_3A_2A_1A_0$	2 4	Rest time	$A_{23} \times 16^1 + A_{22} \times 16^0 =$ RTC time(s) $A_{21} \times 16^1 + A_{20} \times 16^0 =$ FMR1 time(s) $A_{19} \times 16^1 + A_{18} \times 16^0 =$ FMR2 time(s) $A_{17} \times 16^1 + A_{16} \times 16^0 =$ EPS time(s) $A_{15} \times 16^1 + A_{14} \times 16^0 =$ CW time(s) $A_{13} \times 16^1 + A_{12} \times 16^0 =$ CDH1 time(s) $A_{11} \times 16^1 + A_{10} \times 16^0 =$ CDH2 time(s) $A_9 \times 16^1 + A_8 \times 16^0 =$ INF time(s) $A_7 \times 16^1 + A_6 \times 16^0 =$ ADC time(s) $A_5 \times 16^1 + A_4 \times 16^0 =$ CAM1 time(s) $A_3 \times 16^1 + A_2 \times 16^0 =$ CAM2 time(s) $A_1 \times 16^1 + A_0 \times 16^0 =$ CAM3 time(s)

#### 4. CDH1 Sensing Data

**JQ1ZJQ** > **SPROUT**: DBN Data 0x0D  
Callsign      Satellite name      Data Block Number      Carriage return

CDH1 sensing data group	
<b>DBN</b>	Data Block Number
<b>HKD</b>	Housekeeping Data Group

The calculation process of DBN(Data Block Number) shows to chapter 2.1. This data formed hex number.

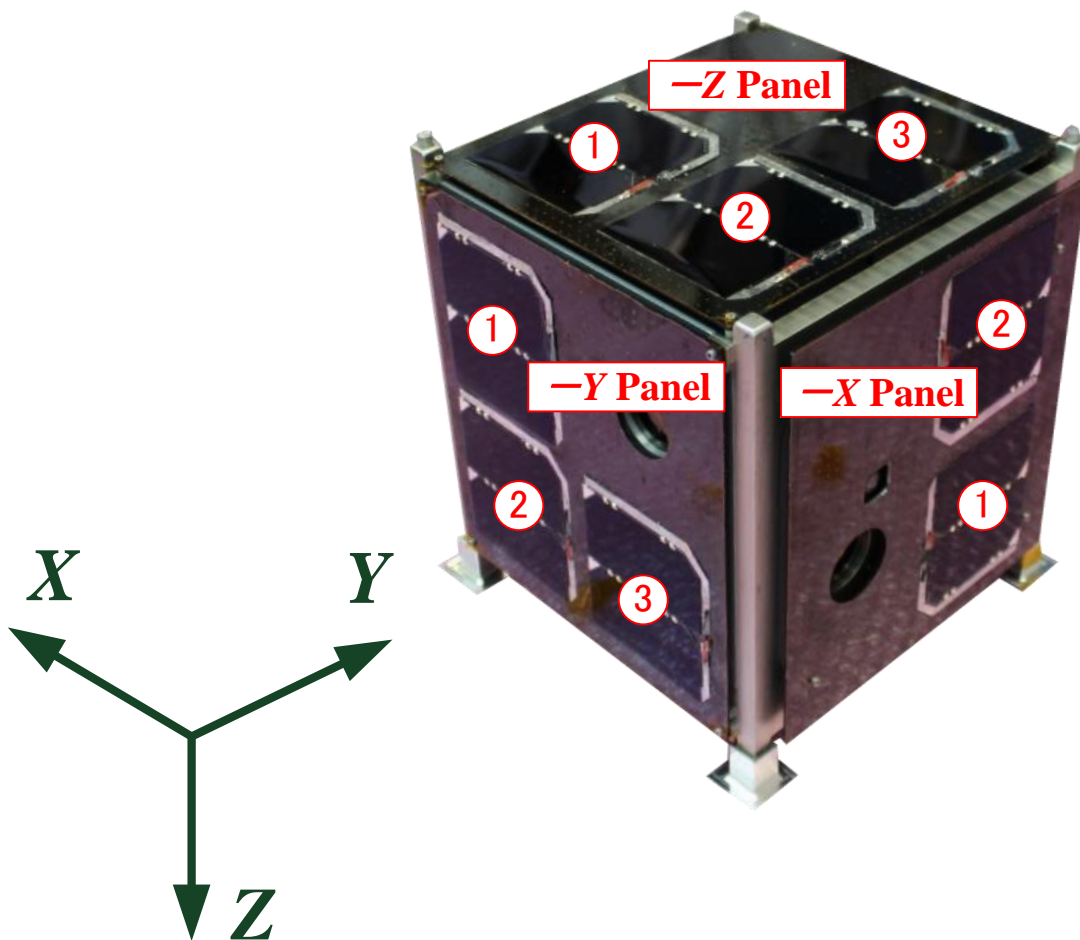
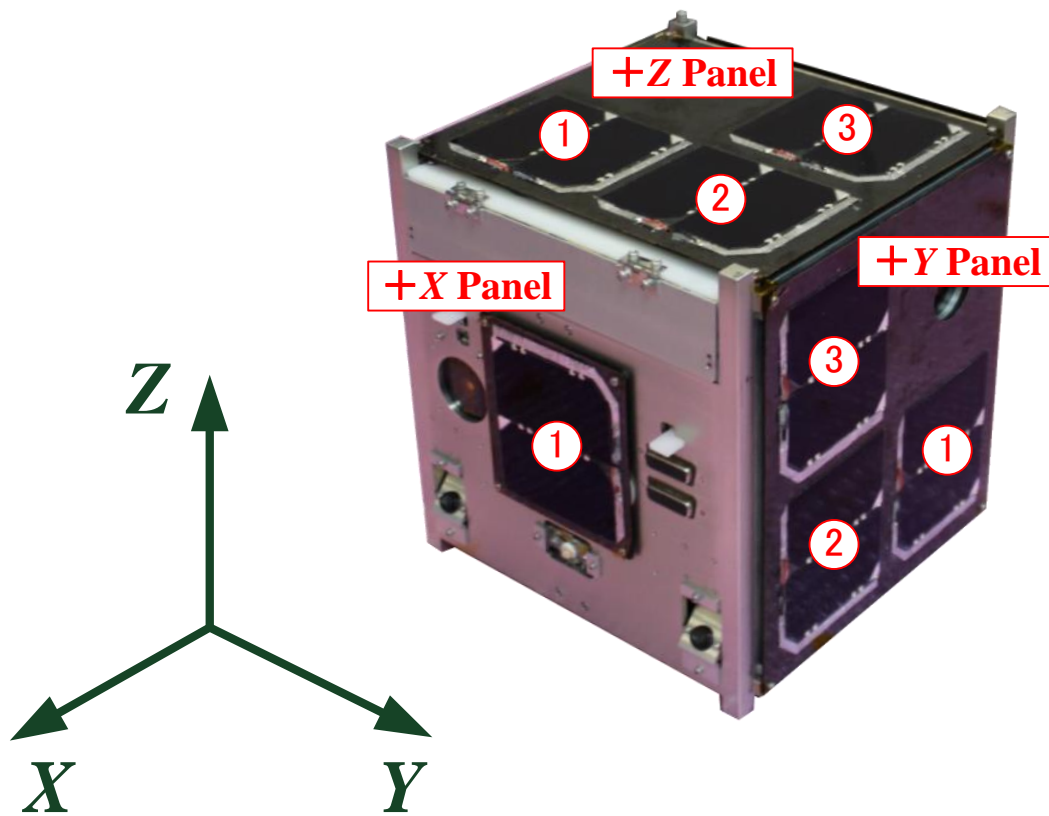
Data group (320 words)															
0 <sub>3</sub> 0 <sub>2</sub>	0 <sub>1</sub> 0 <sub>0</sub>	1 <sub>3</sub> 1 <sub>2</sub>	1 <sub>1</sub> 1 <sub>0</sub>	2 <sub>3</sub> 2 <sub>2</sub>	2 <sub>1</sub> 2 <sub>0</sub>	3 <sub>3</sub> 3 <sub>2</sub>	3 <sub>1</sub> 3 <sub>0</sub>	4 <sub>3</sub> 4 <sub>2</sub>	4 <sub>1</sub> 4 <sub>0</sub>	5 <sub>3</sub> 5 <sub>2</sub>	5 <sub>1</sub> 5 <sub>0</sub>	6 <sub>3</sub> 6 <sub>2</sub>	6 <sub>1</sub> 6 <sub>0</sub>	7 <sub>3</sub> 7 <sub>2</sub>	7 <sub>1</sub> 7 <sub>0</sub>
8 <sub>3</sub> 8 <sub>2</sub>	8 <sub>1</sub> 8 <sub>0</sub>	9 <sub>3</sub> 9 <sub>2</sub>	9 <sub>1</sub> 9 <sub>0</sub>	a <sub>3</sub> a <sub>2</sub>	a <sub>1</sub> a <sub>0</sub>	b <sub>3</sub> b <sub>2</sub>	b <sub>1</sub> b <sub>0</sub>	c <sub>3</sub> c <sub>2</sub>	c <sub>1</sub> c <sub>0</sub>	d <sub>3</sub> d <sub>2</sub>	d <sub>1</sub> d <sub>0</sub>	e <sub>3</sub> e <sub>2</sub>	e <sub>1</sub> e <sub>0</sub>	f <sub>3</sub> f <sub>2</sub>	f <sub>1</sub> f <sub>0</sub>
g <sub>3</sub> g <sub>2</sub>	g <sub>1</sub> g <sub>0</sub>	h <sub>3</sub> h <sub>2</sub>	h <sub>1</sub> h <sub>0</sub>	i <sub>3</sub> i <sub>2</sub>	i <sub>1</sub> i <sub>0</sub>	j <sub>3</sub> j <sub>2</sub>	j <sub>1</sub> j <sub>0</sub>	k <sub>3</sub> k <sub>2</sub>	k <sub>1</sub> k <sub>0</sub>	l <sub>3</sub> l <sub>2</sub>	l <sub>1</sub> l <sub>0</sub>	m <sub>3</sub> m <sub>2</sub>	m <sub>1</sub> m <sub>0</sub>	n <sub>3</sub> n <sub>2</sub>	n <sub>1</sub> n <sub>0</sub>
o <sub>3</sub> o <sub>2</sub>	o <sub>1</sub> o <sub>0</sub>	p <sub>3</sub> p <sub>2</sub>	p <sub>1</sub> p <sub>0</sub>	q <sub>3</sub> q <sub>2</sub>	q <sub>1</sub> q <sub>0</sub>	r <sub>3</sub> r <sub>2</sub>	r <sub>1</sub> r <sub>0</sub>	s <sub>3</sub> s <sub>2</sub>	s <sub>1</sub> s <sub>0</sub>	t <sub>3</sub> t <sub>2</sub>	t <sub>1</sub> t <sub>0</sub>	u <sub>3</sub> u <sub>2</sub>	u <sub>1</sub> u <sub>0</sub>	v <sub>3</sub> v <sub>2</sub>	v <sub>1</sub> v <sub>0</sub>
w <sub>3</sub> w <sub>2</sub>	w <sub>1</sub> w <sub>0</sub>	x <sub>3</sub> x <sub>2</sub>	x <sub>1</sub> x <sub>0</sub>	y <sub>3</sub> y <sub>2</sub>	y <sub>1</sub> y <sub>0</sub>	z <sub>3</sub> z <sub>2</sub>	z <sub>1</sub> z <sub>0</sub>	A <sub>3</sub> A <sub>2</sub>	A <sub>1</sub> A <sub>0</sub>	B <sub>3</sub> B <sub>2</sub>	B <sub>1</sub> B <sub>0</sub>	C <sub>3</sub> C <sub>2</sub>	C <sub>1</sub> C <sub>0</sub>	D <sub>3</sub> D <sub>2</sub>	D <sub>1</sub> D <sub>0</sub>
E <sub>3</sub> E <sub>2</sub>	E <sub>1</sub> E <sub>0</sub>	F <sub>3</sub> F <sub>2</sub>	F <sub>1</sub> F <sub>0</sub>	G <sub>3</sub> G <sub>2</sub>	G <sub>1</sub> G <sub>0</sub>	H <sub>3</sub> H <sub>2</sub>	H <sub>1</sub> H <sub>0</sub>	I <sub>3</sub> I <sub>2</sub>	I <sub>1</sub> I <sub>0</sub>	J <sub>3</sub> J <sub>2</sub>	J <sub>1</sub> J <sub>0</sub>	K <sub>3</sub> K <sub>2</sub>	K <sub>1</sub> K <sub>0</sub>	L <sub>3</sub> L <sub>2</sub>	L <sub>1</sub> L <sub>0</sub>
M <sub>3</sub> M <sub>2</sub>	M <sub>1</sub> M <sub>0</sub>	N <sub>3</sub> N <sub>2</sub>	N <sub>1</sub> N <sub>0</sub>	O <sub>3</sub> O <sub>2</sub>	O <sub>1</sub> O <sub>0</sub>	P <sub>3</sub> P <sub>2</sub>	P <sub>1</sub> P <sub>0</sub>	Q <sub>3</sub> Q <sub>2</sub>	Q <sub>1</sub> Q <sub>0</sub>	R <sub>3</sub> R <sub>2</sub>	R <sub>1</sub> R <sub>0</sub>	S <sub>3</sub> S <sub>2</sub>	S <sub>1</sub> S <sub>0</sub>	T <sub>3</sub> T <sub>2</sub>	T <sub>1</sub> T <sub>0</sub>
U <sub>3</sub> U <sub>2</sub>	U <sub>1</sub> U <sub>0</sub>	V <sub>3</sub> V <sub>2</sub>	V <sub>1</sub> V <sub>0</sub>	W <sub>3</sub> W <sub>2</sub>	W <sub>1</sub> W <sub>0</sub>	X <sub>3</sub> X <sub>2</sub>	X <sub>1</sub> X <sub>0</sub>	Y <sub>3</sub> Y <sub>2</sub>	Y <sub>1</sub> Y <sub>0</sub>	Z <sub>3</sub> Z <sub>2</sub>	Z <sub>1</sub> Z <sub>0</sub>	a <sub>3</sub> a <sub>2</sub>	a <sub>1</sub> a <sub>0</sub>	β <sub>3</sub> β <sub>2</sub>	β <sub>1</sub> β <sub>0</sub>
γ <sub>3</sub> γ <sub>2</sub>	γ <sub>1</sub> γ <sub>0</sub>	δ <sub>3</sub> δ <sub>2</sub>	δ <sub>1</sub> δ <sub>0</sub>	ε <sub>3</sub> ε <sub>2</sub>	ε <sub>1</sub> ε <sub>0</sub>	ζ <sub>3</sub> ζ <sub>2</sub>	ζ <sub>1</sub> ζ <sub>0</sub>	η <sub>3</sub> η <sub>2</sub>	η <sub>1</sub> η <sub>0</sub>	θ <sub>3</sub> θ <sub>2</sub>	θ <sub>1</sub> θ <sub>0</sub>	ι <sub>3</sub> ι <sub>2</sub>	ι <sub>1</sub> ι <sub>0</sub>	κ <sub>3</sub> κ <sub>2</sub>	κ <sub>1</sub> κ <sub>0</sub>
λ <sub>3</sub> λ <sub>2</sub>	λ <sub>1</sub> λ <sub>0</sub>	μ <sub>3</sub> μ <sub>2</sub>	μ <sub>1</sub> μ <sub>0</sub>	ν <sub>3</sub> ν <sub>2</sub>	ν <sub>1</sub> ν <sub>0</sub>	π <sub>3</sub> π <sub>2</sub>	π <sub>1</sub> π <sub>0</sub>	ρ <sub>3</sub> ρ <sub>2</sub>	ρ <sub>1</sub> ρ <sub>0</sub>	σ <sub>3</sub> σ <sub>2</sub>	σ <sub>1</sub> σ <sub>0</sub>				

CDH1 Sensing FM packet structure (total 320 words)				
Group	data	Word(s)	Mean	Calculation
<b>HKD</b>	0 <sub>3</sub> 0 <sub>2</sub> 0 <sub>1</sub> 0 <sub>0</sub>	4	+ X Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	1 <sub>3</sub> 1 <sub>2</sub> 1 <sub>1</sub> 1 <sub>0</sub>	4	- X Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	2 <sub>3</sub> 2 <sub>2</sub> 2 <sub>1</sub> 2 <sub>0</sub>	4	- X Solar Cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	3 <sub>3</sub> 3 <sub>2</sub> 3 <sub>1</sub> 3 <sub>0</sub>	4	- Y Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	4 <sub>3</sub> 4 <sub>2</sub> 4 <sub>1</sub> 4 <sub>0</sub>	4	- Y Solar Cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	5 <sub>3</sub> 5 <sub>2</sub> 5 <sub>1</sub> 5 <sub>0</sub>	4	- Y Solar Cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	6 <sub>3</sub> 6 <sub>2</sub> 6 <sub>1</sub> 6 <sub>0</sub>	4	+ Y Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	7 <sub>3</sub> 7 <sub>2</sub> 7 <sub>1</sub> 7 <sub>0</sub>	4	+ Y Solar Cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	8 <sub>3</sub> 8 <sub>2</sub> 8 <sub>1</sub> 8 <sub>0</sub>	4	+ Y Solar Cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	9 <sub>3</sub> 9 <sub>2</sub> 9 <sub>1</sub> 9 <sub>0</sub>	4	+ Z Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub>	4	+ Z Solar Cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	b <sub>3</sub> b <sub>2</sub> b <sub>1</sub> b <sub>0</sub>	4	+ Z Solar Cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	c <sub>3</sub> c <sub>2</sub> c <sub>1</sub> c <sub>0</sub>	4	- Z Solar Cell 1 generation	$(5 \times x)/(4096 \times 9)$ [A]
	d <sub>3</sub> d <sub>2</sub> d <sub>1</sub> d <sub>0</sub>	4	- Z Solar Cell 2 generation	$(5 \times x)/(4096 \times 9)$ [A]
	e <sub>3</sub> e <sub>2</sub> e <sub>1</sub> e <sub>0</sub>	4	- Z Solar Cell 3 generation	$(5 \times x)/(4096 \times 9)$ [A]
	f <sub>3</sub> f <sub>2</sub> f <sub>1</sub> f <sub>0</sub>	4	Bus current	$(5 \times x)/(4096 \times 0.5)$ [A]

Group	data	Word(s)	Mean	Calculation
HKD	g <sub>3</sub> g <sub>2</sub> g <sub>1</sub> g <sub>0</sub>	4	Bus voltage	$(5 \times x)/4096$ [V]
	h <sub>3</sub> h <sub>2</sub> h <sub>1</sub> h <sub>0</sub>	4	Temperature (Satellite surface +X Panel)	$0.282 \times ((5 \times x)/4096)^2 - 38.98 \times (5 \times x)/4096 + 101.68$ [deg. C]
	i <sub>3</sub> i <sub>2</sub> i <sub>1</sub> i <sub>0</sub>	4	Temperature (Satellite surface +Y Panel)	$0.5777 \times ((5 \times x)/4096)^2 - 40.453 \times (5 \times x)/4096 + 99.226$ [deg. C]
	j <sub>3</sub> j <sub>2</sub> j <sub>1</sub> j <sub>0</sub>	4	Temperature (Satellite surface +Z Panel)	$0.6493 \times ((5 \times x)/4096)^2 - 39.896 \times (5 \times x)/4096 + 98.469$ [deg. C]
	k <sub>3</sub> k <sub>2</sub> k <sub>1</sub> k <sub>0</sub>	4	Temperature (Satellite surface -X Panel)	$0.4105 \times ((5 \times x)/4096)^2 - 39.074 \times (5 \times x)/4096 + 97.993$ [deg. C]
	l <sub>3</sub> l <sub>2</sub> l <sub>1</sub> l <sub>0</sub>	4	Temperature (Satellite surface -Y Panel)	$0.4383 \times ((5 \times x)/4096)^2 - 40.076 \times (5 \times x)/4096 + 98.771$ [deg. C]
	m <sub>3</sub> m <sub>2</sub> m <sub>1</sub> m <sub>0</sub>	4	Temperature (Satellite surface -Z Panel)	$0.2982 \times ((5 \times x)/4096)^2 - 38.98 \times (5 \times x)/4096 + 99.769$ [deg. C]
	n <sub>3</sub> n <sub>2</sub> n <sub>1</sub> n <sub>0</sub>	4	Temperature (Battery 2)	$0.4342 \times ((5 \times x)/4096)^2 - 41.236 \times (5 \times x)/4096 + 103.46$ [deg. C]
	o <sub>3</sub> o <sub>2</sub> o <sub>1</sub> o <sub>0</sub>	4	Temperature (Battery 1)	$0.3995 \times ((5 \times x)/4096)^2 - 40.088 \times (5 \times x)/4096 + 100.84$ [deg. C]
	p <sub>3</sub> p <sub>2</sub> p <sub>1</sub> p <sub>0</sub>	4	Temperature (Reciver2)	$0.3285 \times ((5 \times x)/4096)^2 - 39.376 \times (5 \times x)/4096 + 98.91$ [deg. C]
	q <sub>3</sub> q <sub>2</sub> q <sub>1</sub> q <sub>0</sub>	4	Temperature (Trensmitter2)	$0.2311 \times ((5 \times x)/4096)^2 - 38.955 \times (5 \times x)/4096 + 100.19$ [deg. C]
	r <sub>3</sub> r <sub>2</sub> r <sub>1</sub> r <sub>0</sub>	4	Temperature (Reciver 1)	$0.3281 \times ((5 \times x)/4096)^2 - 39.035 \times (5 \times x)/4096 + 97.608$ [deg. C]
	s <sub>3</sub> s <sub>2</sub> s <sub>1</sub> s <sub>0</sub>	4	Temperature (Transmitter 1)	$0.2946 \times ((5 \times x)/4096)^2 - 39.537 \times (5 \times x)/4096 + 99.7$ [deg. C]
	t <sub>3</sub> t <sub>2</sub> t <sub>1</sub> t <sub>0</sub>	4	Temperature (Gyro sensor Y axis)	$2.1507 \times ((5 \times x)/4096)^2 - 46.004 \times (5 \times x)/4096 + 106.55$ [deg. C]
	u <sub>3</sub> u <sub>2</sub> u <sub>1</sub> u <sub>0</sub>	4	Temperature (Gyro sensor X axis)	$0.7854 \times ((5 \times x)/4096)^2 - 41.015 \times (5 \times x)/4096 + 100.05$ [deg. C]
	v <sub>3</sub> v <sub>2</sub> v <sub>1</sub> v <sub>0</sub>	4	Temperature (Gyro sensor Z axis)	$0.9648 \times ((5 \times x)/4096)^2 - 39.886 \times (5 \times x)/4096 + 108.37$ [deg. C]
	w <sub>3</sub> w <sub>2</sub> w <sub>1</sub> w <sub>0</sub>	4	Temperature (Magnetic field sensor)	$0.0728 \times ((5 \times x)/4096)^2 - 36.191 \times (5 \times x)/4096 + 95.367$ [deg. C]
	x <sub>3</sub> x <sub>2</sub> x <sub>1</sub> x <sub>0</sub>	4	Temperature (Magnetic valve 1)	$0.1777 \times ((5 \times x)/4096)^2 - 38.862 \times (5 \times x)/4096 + 98.819$ [deg. C]
	y <sub>3</sub> y <sub>2</sub> y <sub>1</sub> y <sub>0</sub>	4	Temperature (storage box top)	$0.7649 \times ((5 \times x)/4096)^2 - 41.38 \times (5 \times x)/4096 + 101.98$ [deg. C]
	z <sub>3</sub> z <sub>2</sub> z <sub>1</sub> z <sub>0</sub>	4	Temperature (ADC board)	$0.2936 \times ((5 \times x)/4096)^2 - 39.207 \times (5 \times x)/4096 + 99.713$ [deg. C]
	A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub>	4	Temperature (EPS board)	$0.3051 \times ((5 \times x)/4096)^2 - 39.009 \times (5 \times x)/4096 + 99.257$ [deg. C]
	B <sub>3</sub> B <sub>2</sub> B <sub>1</sub> B <sub>0</sub>	4	Temperature (CDH1 board)	$0.3241 \times ((5 \times x)/4096)^2 - 39.444 \times (5 \times x)/4096 + 100.56$ [deg. C]
	C <sub>3</sub> C <sub>2</sub> C <sub>1</sub> C <sub>0</sub>	4	Temperature (CAM3 board)	$0.3862 \times ((5 \times x)/4096)^2 - 39.157 \times (5 \times x)/4096 + 100.05$ [deg. C]
	D <sub>3</sub> D <sub>2</sub> D <sub>1</sub> D <sub>0</sub>	4	Temperature (FMR1 board)	$0.3366 \times ((5 \times x)/4096)^2 - 39.025 \times (5 \times x)/4096 + 98.665$ [deg. C]
	E <sub>3</sub> E <sub>2</sub> E <sub>1</sub> E <sub>0</sub>	4	Temperature (bottom of membrane)	$0.0832 \times ((5 \times x)/4096)^2 - 38.109 \times (5 \times x)/4096 + 96.654$ [deg. C]
	F <sub>3</sub> F <sub>2</sub> F <sub>1</sub> F <sub>0</sub>	4	Temperature (InflatableTube 1)	$0.1625 \times ((5 \times x)/4096)^2 - 38.356 \times (5 \times x)/4096 + 98.533$ [deg. C]
	G <sub>3</sub> G <sub>2</sub> G <sub>1</sub> G <sub>0</sub>	4	Temperature (InflatableTube2)	$0.0357 \times ((5 \times x)/4096)^2 - 37.908 \times (5 \times x)/4096 + 98.005$ [deg. C]
	H <sub>3</sub> H <sub>2</sub> H <sub>1</sub> H <sub>0</sub>	4	Temperatue (Inside pipe)	$0.3021 \times ((5 \times x)/4096)^2 - 39.42 \times (5 \times x)/4096 + 98.922$ [deg. C]

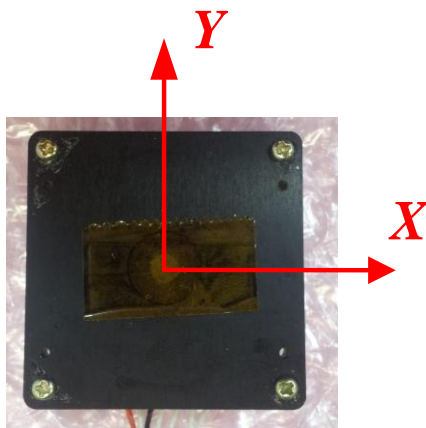
Group	data	Word(s)	Mean	Calculation
HKD	I <sub>3</sub> I <sub>2</sub> I <sub>1</sub> I <sub>0</sub>	4	Temperature (Inside storage box)	$-0.0318 \times ((5 \times x)/4096)^2 - 37.221 \times (5 \times x)/4096 + 98.686$ [deg. C]
	J <sub>3</sub> J <sub>2</sub> J <sub>1</sub> J <sub>0</sub>	4	Pressure sensor Primary pressure	$(20689.66 \times x)/4096$ [kPa]
	K <sub>3</sub> K <sub>2</sub> K <sub>1</sub> K <sub>0</sub>	4	Pressure sensor Secondly pressure	$(206.90 \times x)/4096$ [kPa]
	L <sub>3</sub> L <sub>2</sub> L <sub>1</sub> L <sub>0</sub>	4	No-Data	–
	M <sub>3</sub> M <sub>2</sub> M <sub>1</sub> M <sub>0</sub>	4	Magnetic field sensor Ref value	$V_{ref} = (5 \times x)/4096$ Ref (V <sub>ref</sub> )value uses for calculate parameter of magnetic field sensor
	N <sub>3</sub> N <sub>2</sub> N <sub>1</sub> N <sub>0</sub>	4	Magnetic field sensor Y axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	O <sub>3</sub> O <sub>2</sub> O <sub>1</sub> O <sub>0</sub>	4	Magnetic field sensor X axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	P <sub>3</sub> P <sub>2</sub> P <sub>1</sub> P <sub>0</sub>	4	Magnetic field sensor Z axis	$(5 \times x)/4096 - V_{ref}$ [gauss]
	Q <sub>3</sub> Q <sub>2</sub> Q <sub>1</sub> Q <sub>0</sub>	4	Gyro sensor Y axis	$((5 \times x)/4096 - 2.4824)/1.1288$ [rad/s]
	R <sub>3</sub> R <sub>2</sub> R <sub>1</sub> R <sub>0</sub>	4	Gyro sensor X axis	$-((5 \times x)/4096 - 2.4913)/1.1309$ [rad/s]
	S <sub>3</sub> S <sub>2</sub> S <sub>1</sub> S <sub>0</sub>	4	Gyro sensor Z axis	$((5 \times x)/4096 - 2.4752)/1.1199$ [rad/s]
	T <sub>3</sub> T <sub>2</sub> T <sub>1</sub> T <sub>0</sub>	4	Non-Data	–
	U <sub>3</sub> U <sub>2</sub> U <sub>1</sub> U <sub>0</sub>	4	Sun sensor 1 +X	$(5 \times x)/4096$ [V]
	V <sub>3</sub> V <sub>2</sub> V <sub>1</sub> V <sub>0</sub>	4	Sun sensor 1 –X	$(5 \times x)/4096$ [V]
	W <sub>3</sub> W <sub>2</sub> W <sub>1</sub> W <sub>0</sub>	4	Sun sensor 1 +Y	$(5 \times x)/4096$ [V]
	X <sub>3</sub> X <sub>2</sub> X <sub>1</sub> X <sub>0</sub>	4	Sun sensor 1 –Y	$(5 \times x)/4096$ [V]
	Y <sub>3</sub> Y <sub>2</sub> Y <sub>1</sub> Y <sub>0</sub>	4	Sun sensor 2 +X	$(5 \times x)/4096$ [V]
	Z <sub>3</sub> Z <sub>2</sub> Z <sub>1</sub> Z <sub>0</sub>	4	Sun sensor 2 –X	$(5 \times x)/4096$ [V]
	a <sub>3</sub> a <sub>2</sub> a <sub>1</sub> a <sub>0</sub>	4	Sun sensor 2 +Y	$(5 \times x)/4096$ [V]
	β <sub>3</sub> β <sub>2</sub> β <sub>1</sub> β <sub>0</sub>	4	Sun sensor 2 –Y	$(5 \times x)/4096$ [V]
	γ <sub>3</sub> γ <sub>2</sub> γ <sub>1</sub> γ <sub>0</sub>	4	Sun sensor 4 –Y	$(5 \times x)/4096$ [V]
	δ <sub>3</sub> δ <sub>2</sub> δ <sub>1</sub> δ <sub>0</sub>	4	Sun sensor 4 +Y	$(5 \times x)/4096$ [V]
	ε <sub>3</sub> ε <sub>2</sub> ε <sub>1</sub> ε <sub>0</sub>	4	Sun sensor 4 –X	$(5 \times x)/4096$ [V]
	ζ <sub>3</sub> ζ <sub>2</sub> ζ <sub>1</sub> ζ <sub>0</sub>	4	Sun sensor 4 +X	$(5 \times x)/4096$ [V]
	η <sub>3</sub> η <sub>2</sub> η <sub>1</sub> η <sub>0</sub>	4	Sun sensor 3 –Y	$(5 \times x)/4096$ [V]
	θ <sub>3</sub> θ <sub>2</sub> θ <sub>1</sub> θ <sub>0</sub>	4	Sun sensor 3 +Y	$(5 \times x)/4096$ [V]
	ι <sub>3</sub> ι <sub>2</sub> ι <sub>1</sub> ι <sub>0</sub>	4	Sun sensor 3 –X	$(5 \times x)/4096$ [V]
	κ <sub>3</sub> κ <sub>2</sub> κ <sub>1</sub> κ <sub>0</sub>	4	Sun sensor 3 +X	$(5 \times x)/4096$ [V]
	λ <sub>3</sub> λ <sub>2</sub> λ <sub>1</sub> λ <sub>0</sub>	4	Sun sensor 6 –Y	$(5 \times x)/4096$ [V]
	μ <sub>3</sub> μ <sub>2</sub> μ <sub>1</sub> μ <sub>0</sub>	4	Sun sensor 6 +Y	$(5 \times x)/4096$ [V]
	ν <sub>3</sub> ν <sub>2</sub> ν <sub>1</sub> ν <sub>0</sub>	4	Sun sensor 6 –X	$(5 \times x)/4096$ [V]
	ξ <sub>3</sub> ξ <sub>2</sub> ξ <sub>1</sub> ξ <sub>0</sub>	4	Sun sensor 6 +X	$(5 \times x)/4096$ [V]
	ο <sub>3</sub> ο <sub>2</sub> ο <sub>1</sub> ο <sub>0</sub>	4	Sun sensor 5 –Y	$(5 \times x)/4096$ [V]
	π <sub>3</sub> π <sub>2</sub> π <sub>1</sub> π <sub>0</sub>	4	Sun sensor 5 +Y	$(5 \times x)/4096$ [V]
	ρ <sub>3</sub> ρ <sub>2</sub> ρ <sub>1</sub> ρ <sub>0</sub>	4	Sun sensor 5 –X	$(5 \times x)/4096$ [V]
	σ <sub>3</sub> σ <sub>2</sub> σ <sub>1</sub> σ <sub>0</sub>	4	Sun sensor 5 +X	$(5 \times x)/4096$ [V]

## 5. The Coordinate System of SPROUT and Solar Cell Number

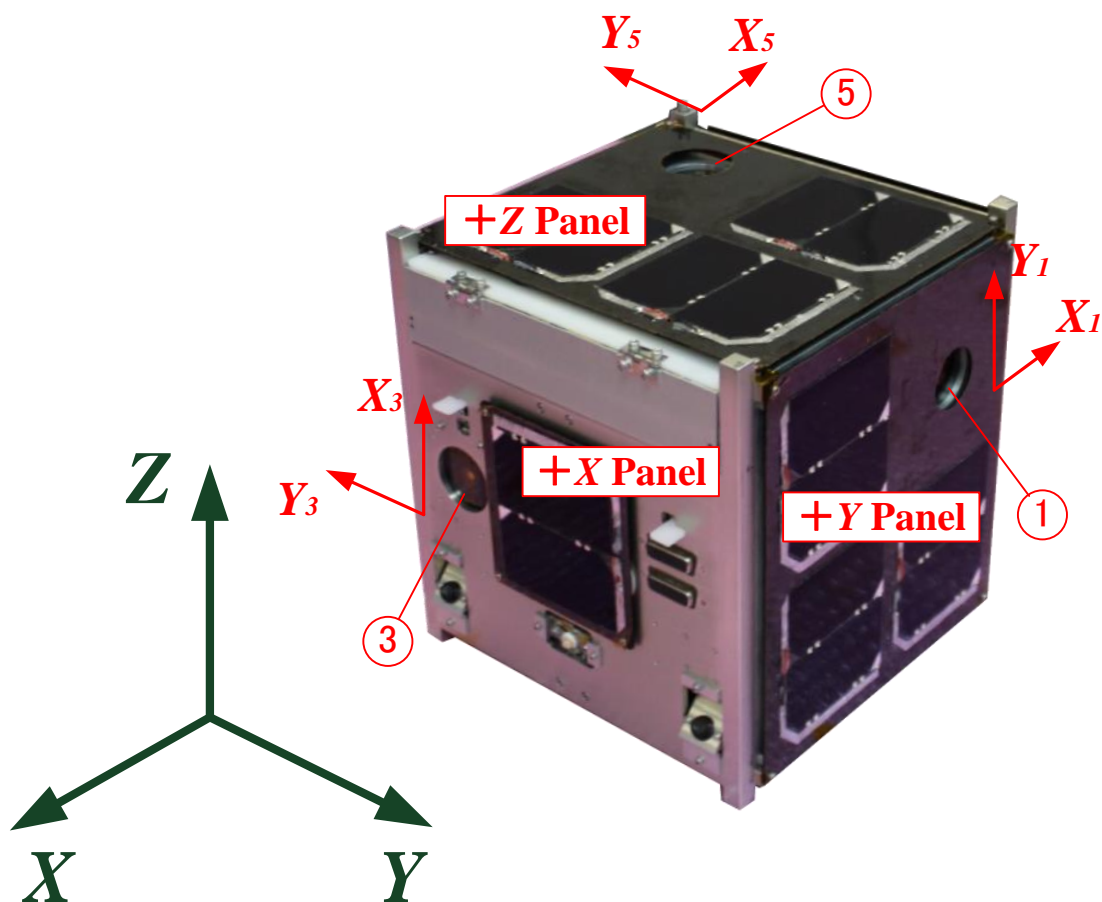


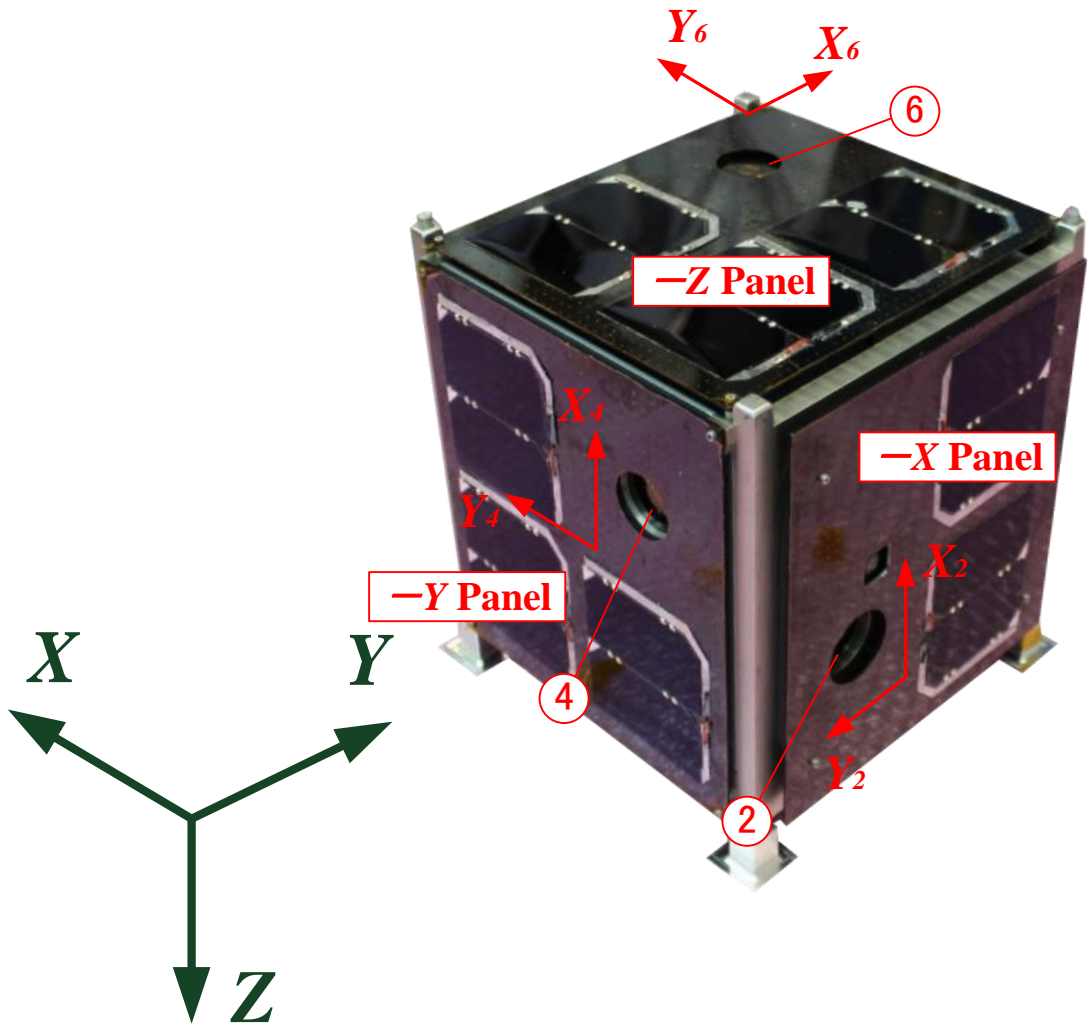
## 6. The Relationship between Coordinate System and Sun Sensor

The SPROUT has six sun sensors. And, each sensor keep coordinate system( shows below).



So it needs to know where the sun sensors are. This is the relationship between coordinate system and sun sensor.





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